

# MSM519200

**4,194,304-Word × 2-Bit DYNAMIC RAM : FAST PAGE MODE TYPE**

## DESCRIPTION

The MSM519200 is a 4,194,304-word × 2-bit dynamic RAM fabricated in Oki's silicon-gate CMOS technology. The MSM519200 achieves high integration, high-speed operation, and low-power consumption because Oki manufactures the device in a quadruple-layer polysilicon/double-layer metal CMOS process. The MSM519200 is available in a 26/24-pin plastic SOJ or 26/24-pin plastic TSOP.

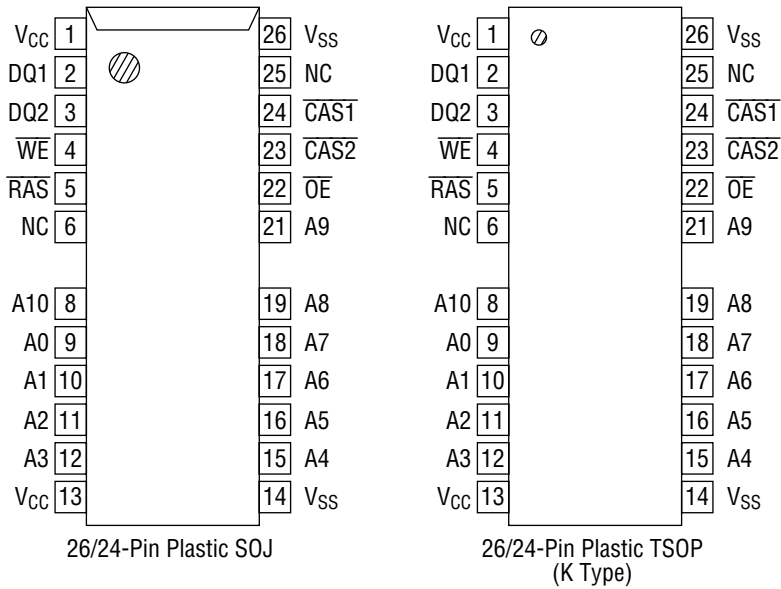
## FEATURES

- 4,194,304-word × 2-bit configuration
  - Single 5 V power supply, ±10% tolerance
  - Input : TTL compatible, low input capacitance
  - Output : TTL compatible, 3-state
  - Refresh : 2048 cycles/32 ms
  - Fast page mode, read modify write capability
  - $\overline{\text{CAS}}$  before  $\overline{\text{RAS}}$  refresh, hidden refresh,  $\overline{\text{RAS}}$ -only refresh capability
  - Multi-bit test mode capability
  - Package options:
    - 26/24-pin 300 mil plastic SOJ (SOJ26/24-P-300-1.27) (Product : MSM519200-xxSJ)
    - 26/24-pin 300 mil plastic TSOP (TSOPII26/24-P-300-1.27-K) (Product : MSM519200-xxTS-K)
- xx indicates speed rank.

## PRODUCT FAMILY

Family	Access Time (Max.)				Cycle Time (Min.)	Power Dissipation	
	t <sub>RAC</sub>	t <sub>AA</sub>	t <sub>CAC</sub>	t <sub>OEA</sub>		Operating (Max.)	Standby (Max.)
MSM519200-60	60 ns	30 ns	15 ns	15 ns	110 ns	440 mW	5.5 mW
MSM519200-70	70 ns	35 ns	20 ns	20 ns	130 ns	413 mW	
MSM519200-80	80 ns	40 ns	20 ns	20 ns	150 ns	385 mW	

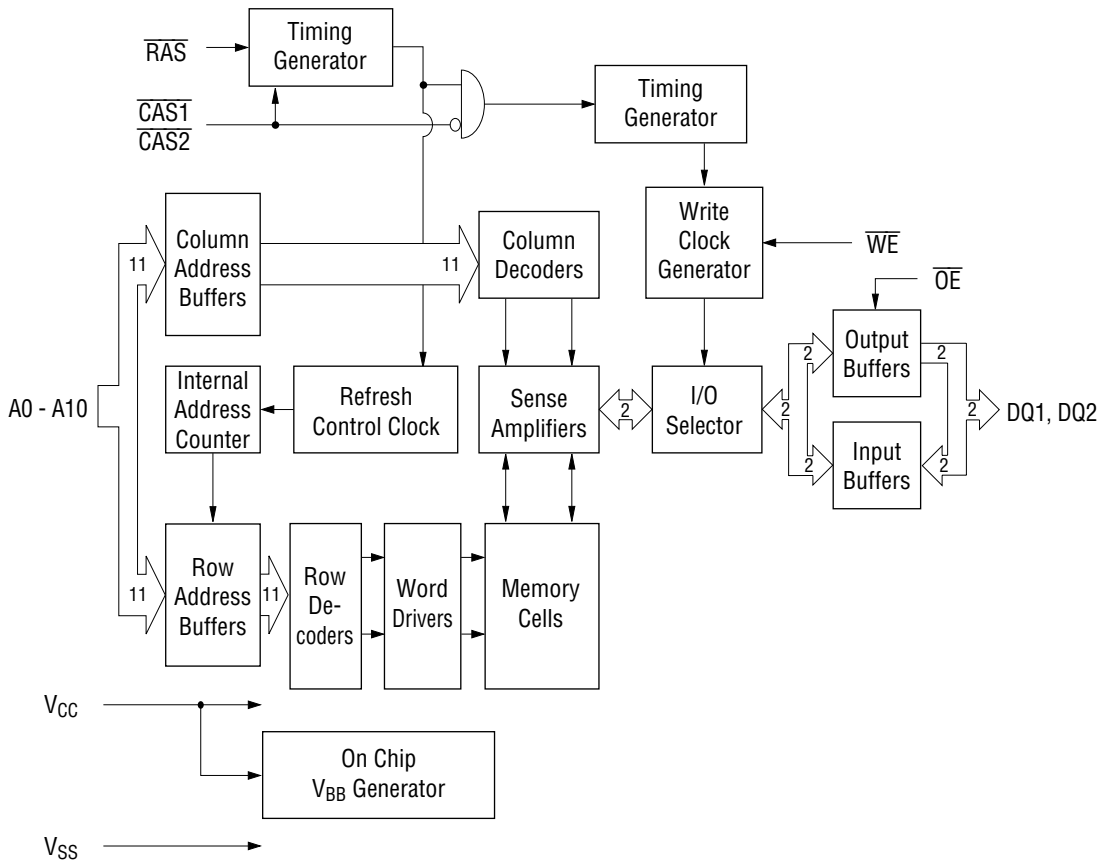
**PIN CONFIGURATION (TOP VIEW)**



Pin Name	Function
A0 - A10	Address Input
$\overline{\text{RAS}}$	Row Address Strobe
$\overline{\text{CAS1}}, \overline{\text{CAS2}}$	Column Address Strobe
DQ1, DQ2	Data Input/Data Output
$\overline{\text{OE}}$	Output Enable
$\overline{\text{WE}}$	Write Enable
V <sub>CC</sub>	Power Supply (5 V)
V <sub>SS</sub>	Ground (0 V)
NC	No Connection

Note : The same power supply voltage must be provided to every V<sub>CC</sub> pin, and the same GND voltage level must be provided to every V<sub>SS</sub> pin.

**BLOCK DIAGRAM**



**FUNCTION TABLE**

Input Pin					DQ Pin		Function Mode
RAS	CAS1	CAS2	WE	OE	DQ1	DQ2	
H	*	*	*	*	High-Z	High-Z	Standby
L	H	H	*	*	High-Z	High-Z	Refresh
L	L	H	H	L	D <sub>OUT</sub>	High-Z	DQ1 Read
L	H	L	H	L	High-Z	D <sub>OUT</sub>	DQ2 Read
L	L	L	H	L	D <sub>OUT</sub>	D <sub>OUT</sub>	DQ1, DQ2 Read
L	L	H	L	H	D <sub>IN</sub>	Don't Care	DQ1 Write
L	H	L	L	H	Don't Care	D <sub>IN</sub>	DQ2 Write
L	L	L	L	H	D <sub>IN</sub>	D <sub>IN</sub>	DQ1, DQ2 Write
L	L	L	H	H	High-Z	High-Z	—

\*: "H" or "L"

## ELECTRICAL CHARACTERISTICS

### Absolute Maximum Ratings

Parameter	Symbol	Rating	Unit
Voltage on Any Pin Relative to $V_{SS}$	$V_T$	-1.0 to 7.0	V
Short Circuit Output Current	$I_{OS}$	50	mA
Power Dissipation	$P_D^*$	1	W
Operating Temperature	$T_{opr}$	0 to 70	°C
Storage Temperature	$T_{stg}$	-55 to 150	°C

\*:  $T_a = 25^\circ\text{C}$

### Recommended Operating Conditions

( $T_a = 0^\circ\text{C}$  to  $70^\circ\text{C}$ )

Parameter	Symbol	Min.	Typ.	Max.	Unit
Power Supply Voltage	$V_{CC}$	4.5	5.0	5.5	V
	$V_{SS}$	0	0	0	V
Input High Voltage	$V_{IH}$	2.4	—	6.5	V
Input Low Voltage	$V_{IL}$	-1.0	—	0.8	V

### Capacitance

( $V_{CC} = 5\text{ V} \pm 10\%$ ,  $T_a = 25^\circ\text{C}$ ,  $f = 1\text{ MHz}$ )

Parameter	Symbol	Typ.	Max.	Unit
Input Capacitance (A0 - A10)	$C_{IN1}$	—	6	pF
Input Capacitance ( $\overline{\text{RAS}}$ , $\overline{\text{CAS1}}$ , $\overline{\text{CAS2}}$ , $\overline{\text{WE}}$ , $\overline{\text{OE}}$ )	$C_{IN2}$	—	7	pF
Output Capacitance (DQ1, DQ2)	$C_{I/O}$	—	10	pF

DC Characteristics

(V<sub>CC</sub> = 5 V ±10%, T<sub>a</sub> = 0°C to 70°C)

Parameter	Symbol	Condition	MSM519200 -60		MSM519200 -70		MSM519200 -80		Unit	Note
			Min.	Max.	Min.	Max.	Min.	Max.		
Output High Voltage	V <sub>OH</sub>	I <sub>OH</sub> = -5.0 mA	2.4	V <sub>CC</sub>	2.4	V <sub>CC</sub>	2.4	V <sub>CC</sub>	V	
Output Low Voltage	V <sub>OL</sub>	I <sub>OL</sub> = 4.2 mA	0	0.4	0	0.4	0	0.4	V	
Input Leakage Current	I <sub>LI</sub>	0 V ≤ V <sub>I</sub> ≤ 6.5 V; All other pins not under test = 0 V	-10	10	-10	10	-10	10	μA	
Output Leakage Current	I <sub>LO</sub>	DQ disable 0 V ≤ V <sub>O</sub> ≤ 5.5 V	-10	10	-10	10	-10	10	μA	
Average Power Supply Current (Operating)	I <sub>CC1</sub>	RAS, CAS1, CAS2 cycling, t <sub>RC</sub> = Min.	—	80	—	75	—	70	mA	1, 2
Power Supply Current (Standby)	I <sub>CC2</sub>	RAS, CAS1, CAS2 = V <sub>IH</sub> RAS, CAS1, CAS2 ≥ V <sub>CC</sub> - 0.2 V	—	2	—	2	—	2	mA	1
Average Power Supply Current (RAS-only Refresh)	I <sub>CC3</sub>	RAS cycling, CAS1, CAS2 = V <sub>IH</sub> , t <sub>RC</sub> = Min.	—	80	—	75	—	70	mA	1, 2
Power Supply Current (Standby)	I <sub>CC5</sub>	RAS = V <sub>IH</sub> , CAS1, CAS2 = V <sub>IL</sub> , DQ = enable	—	5	—	5	—	5	mA	1
Average Power Supply Current (CAS before RAS Refresh)	I <sub>CC6</sub>	RAS cycling, CAS1, CAS2 before RAS	—	80	—	75	—	70	mA	1, 2
Average Power Supply Current (Fast Page Mode)	I <sub>CC7</sub>	RAS = V <sub>IL</sub> , CAS1, CAS2 cycling, t <sub>PC</sub> = Min.	—	70	—	65	—	60	mA	1, 3

- Notes :
1. I<sub>CC</sub> Max. is specified as I<sub>CC</sub> for output open condition.
  2. The address can be changed once or less while RAS = V<sub>IL</sub>.
  3. The address can be changed once or less while CAS1, CAS2 = V<sub>IH</sub>.

AC Characteristics (1/2)

(V<sub>CC</sub> = 5 V ±10%, T<sub>a</sub> = 0°C to 70°C) Note 1, 2, 3, 11, 12

Parameter	Symbol	MSM519200 -60		MSM519200 -70		MSM519200 -80		Unit	Note
		Min.	Max.	Min.	Max.	Min.	Max.		
Random Read or Write Cycle Time	t <sub>RC</sub>	110	—	130	—	150	—	ns	
Read Modify Write Cycle Time	t <sub>RWC</sub>	155	—	185	—	205	—	ns	
Fast Page Mode Cycle Time	t <sub>PC</sub>	40	—	45	—	50	—	ns	
Fast Page Mode Read Modify Write Cycle Time	t <sub>PRWC</sub>	85	—	100	—	105	—	ns	
Access Time from $\overline{\text{RAS}}$	t <sub>RAC</sub>	—	60	—	70	—	80	ns	4, 5, 6
Access Time from $\overline{\text{CAS}}$	t <sub>CAC</sub>	—	15	—	20	—	20	ns	4, 5
Access Time from Column Address	t <sub>AA</sub>	—	30	—	35	—	40	ns	4, 6
Access Time from $\overline{\text{CAS}}$ Precharge	t <sub>CPA</sub>	—	35	—	40	—	45	ns	4, 14
Access Time from $\overline{\text{OE}}$	t <sub>OEA</sub>	—	15	—	20	—	20	ns	4
Output Low Impedance Time from $\overline{\text{CAS}}$	t <sub>CLZ</sub>	0	—	0	—	0	—	ns	4
$\overline{\text{CAS}}$ to Data Output Buffer Turn-off Delay Time	t <sub>OFF</sub>	0	15	0	20	0	20	ns	7
$\overline{\text{OE}}$ to Data Output Buffer Turn-off Delay Time	t <sub>OEZ</sub>	0	15	0	20	0	20	ns	7
Transition Time	t <sub>T</sub>	3	50	3	50	3	50	ns	3
Refresh Period	t <sub>REF</sub>	—	32	—	32	—	32	ms	
$\overline{\text{RAS}}$ Precharge Time	t <sub>RP</sub>	40	—	50	—	60	—	ns	
$\overline{\text{RAS}}$ Pulse Width	t <sub>RAS</sub>	60	10,000	70	10,000	80	10,000	ns	
$\overline{\text{RAS}}$ Pulse Width (Fast Page Mode)	t <sub>RASP</sub>	60	100,000	70	100,000	80	100,000	ns	
$\overline{\text{RAS}}$ Hold Time	t <sub>RSH</sub>	15	—	20	—	20	—	ns	
$\overline{\text{RAS}}$ Hold Time referenced to $\overline{\text{OE}}$	t <sub>ROH</sub>	10	—	10	—	10	—	ns	
$\overline{\text{CAS}}$ Precharge Time (Fast Page Mode)	t <sub>CP</sub>	10	—	10	—	10	—	ns	16
$\overline{\text{CAS}}$ Pulse Width	t <sub>CAS</sub>	15	10,000	20	10,000	20	10,000	ns	
$\overline{\text{CAS}}$ Hold Time	t <sub>CSH</sub>	60	—	70	—	80	—	ns	
$\overline{\text{CAS}}$ to $\overline{\text{RAS}}$ Precharge Time	t <sub>CRP</sub>	10	—	10	—	10	—	ns	14
$\overline{\text{RAS}}$ Hold Time from $\overline{\text{CAS}}$ Precharge	t <sub>RHCP</sub>	35	—	40	—	45	—	ns	
$\overline{\text{RAS}}$ to $\overline{\text{CAS}}$ Delay Time	t <sub>RCD</sub>	20	45	20	50	20	60	ns	5
$\overline{\text{RAS}}$ to Column Address Delay Time	t <sub>RAD</sub>	15	30	15	35	15	40	ns	6
Row Address Set-up Time	t <sub>ASR</sub>	0	—	0	—	0	—	ns	
Row Address Hold Time	t <sub>RAH</sub>	10	—	10	—	10	—	ns	
Column Address Set-up Time	t <sub>ASC</sub>	0	—	0	—	0	—	ns	13
Column Address Hold Time	t <sub>CAH</sub>	15	—	15	—	15	—	ns	13
Column Address Hold Time from $\overline{\text{RAS}}$	t <sub>AR</sub>	50	—	55	—	60	—	ns	
Column Address to $\overline{\text{RAS}}$ Lead Time	t <sub>RAL</sub>	30	—	35	—	40	—	ns	
Read Command Set-up Time	t <sub>RCS</sub>	0	—	0	—	0	—	ns	13
Read Command Hold Time	t <sub>RCH</sub>	0	—	0	—	0	—	ns	8, 13
Read Command Hold Time referenced to $\overline{\text{RAS}}$	t <sub>RRH</sub>	0	—	0	—	0	—	ns	8

AC Characteristics (2/2)

(V<sub>CC</sub> = 5 V ±10%, T<sub>a</sub> = 0°C to 70°C) Note 1, 2, 3, 11, 12

Parameter	Symbol	MSM519200 -60		MSM519200 -70		MSM519200 -80		Unit	Note
		Min.	Max.	Min.	Max.	Min.	Max.		
Write Command Set-up Time	t <sub>WCS</sub>	0	—	0	—	0	—	ns	9, 13
Write Command Hold Time	t <sub>WCH</sub>	10	—	15	—	15	—	ns	13
Write Command Hold Time from RAS	t <sub>WCR</sub>	45	—	55	—	60	—	ns	
Write Command Pulse Width	t <sub>WP</sub>	10	—	10	—	10	—	ns	
OE Command Hold Time	t <sub>OEH</sub>	15	—	20	—	20	—	ns	
Write Command to RAS Lead Time	t <sub>RWL</sub>	15	—	20	—	20	—	ns	
Write Command to CAS Lead Time	t <sub>CWL</sub>	15	—	20	—	20	—	ns	15
Data-in Set-up Time	t <sub>DS</sub>	0	—	0	—	0	—	ns	10, 13
Data-in Hold Time	t <sub>DH</sub>	15	—	15	—	15	—	ns	10, 13
Data-in Hold Time from RAS	t <sub>DHR</sub>	50	—	55	—	60	—	ns	
OE to Data-in Delay Time	t <sub>OED</sub>	15	—	20	—	20	—	ns	
CAS to WE Delay Time	t <sub>CWD</sub>	40	—	50	—	50	—	ns	9
Column Address to WE Delay Time	t <sub>AWD</sub>	55	—	65	—	70	—	ns	9
RAS to WE Delay Time	t <sub>RWD</sub>	85	—	100	—	110	—	ns	9
CAS Precharge WE Delay Time	t <sub>CPWD</sub>	60	—	70	—	75	—	ns	9, 14
CAS Active Delay Time from RAS Precharge	t <sub>RPC</sub>	10	—	10	—	10	—	ns	13
RAS to CAS Set-up Time (CAS before RAS)	t <sub>CSR</sub>	10	—	10	—	10	—	ns	13
RAS to CAS Hold Time (CAS before RAS)	t <sub>CHR</sub>	20	—	20	—	20	—	ns	14
WE to RAS Precharge Time (CAS before RAS)	t <sub>WRP</sub>	10	—	10	—	10	—	ns	
WE Hold Time from RAS (CAS before RAS)	t <sub>WRH</sub>	10	—	10	—	10	—	ns	
RAS to WE Set-up Time (Test Mode)	t <sub>WTS</sub>	10	—	10	—	10	—	ns	
RAS to WE Hold Time (Test Mode)	t <sub>WTH</sub>	20	—	20	—	20	—	ns	

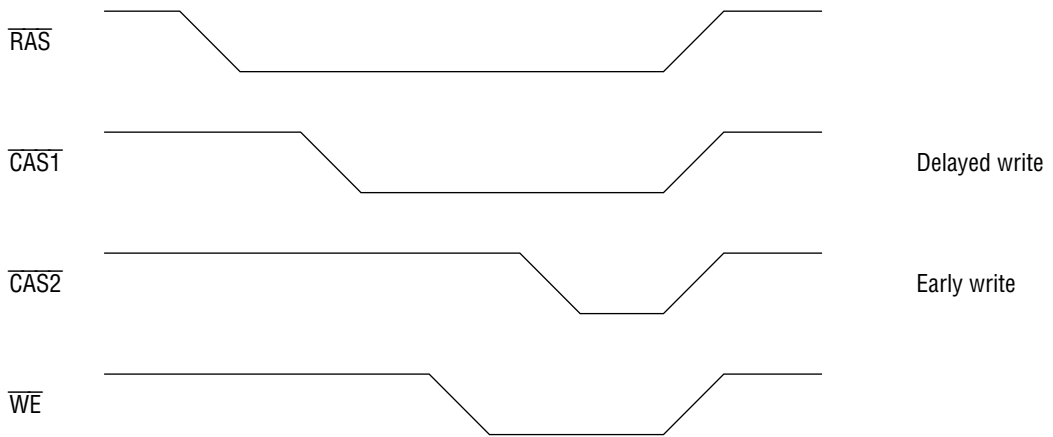
- Notes:
1. A start-up delay of 200  $\mu$ s is required after power-up, followed by a minimum of eight initialization cycles ( $\overline{\text{RAS}}$ -only refresh or  $\overline{\text{CAS}}$  before  $\overline{\text{RAS}}$  refresh) before proper device operation is achieved.
  2. The AC characteristics assume  $t_T = 5$  ns.
  3.  $V_{IH}$  (Min.) and  $V_{IL}$  (Max.) are reference levels for measuring input timing signals. Transition times ( $t_T$ ) are measured between  $V_{IH}$  and  $V_{IL}$ .
  4. This parameter is measured with a load circuit equivalent to 2 TTL loads and 100 pF.
  5. Operation within the  $t_{RCD}$  (Max.) limit ensures that  $t_{RAC}$  (Max.) can be met.  $t_{RCD}$  (Max.) is specified as a reference point only. If  $t_{RCD}$  is greater than the specified  $t_{RCD}$  (Max.) limit, then the access time is controlled by  $t_{CAC}$ .
  6. Operation within the  $t_{RAD}$  (Max.) limit ensures that  $t_{RAC}$  (Max.) can be met.  $t_{RAD}$  (Max.) is specified as a reference point only. If  $t_{RAD}$  is greater than the specified  $t_{RAD}$  (Max.) limit, then the access time is controlled by  $t_{AA}$ .
  7.  $t_{OFF}$  (Max.) and  $t_{OEZ}$  (Max.) define the time at which the output achieves the open circuit condition and are not referenced to output voltage levels.
  8.  $t_{RCH}$  or  $t_{RRH}$  must be satisfied for a read cycle.
  9.  $t_{WCS}$ ,  $t_{CWD}$ ,  $t_{RWD}$ ,  $t_{AWD}$  and  $t_{CPWD}$  are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only. If  $t_{WCS} \geq t_{WCS}$  (Min.), then the cycle is an early write cycle and the data out will remain open circuit (high impedance) throughout the entire cycle. If  $t_{CWD} \geq t_{CWD}$  (Min.),  $t_{RWD} \geq t_{RWD}$  (Min.),  $t_{AWD} \geq t_{AWD}$  (Min.) and  $t_{CPWD} \geq t_{CPWD}$  (Min.), then the cycle is a read modify write cycle and data out will contain data read from the selected cell; if neither of the above sets of conditions is satisfied, then the condition of the data out (at access time) is indeterminate.
  10. These parameters are referenced to the  $\overline{\text{CAS}}$  leading edge in an early write cycle, and to the  $\overline{\text{WE}}$  leading edge in an  $\overline{\text{OE}}$  control write cycle, or a read modify write cycle.
  11. The test mode is initiated by performing a  $\overline{\text{WE}}$  and  $\overline{\text{CAS}}$  before  $\overline{\text{RAS}}$  refresh cycle. This mode is latched and remains in effect until the exit cycle is generated. In a test mode CA0, CA1 and CA10 are not used and each DQ pin now accesses 8-bit locations. Since all 2 DQ pins are used, a total of 16 data bits can be written in parallel into the memory array. In a read cycle, if 8 data bits are equal, the DQ pin will indicate a high level. If the 8 data bits are not equal, the DQ pin will indicate a low level. The test mode is cleared and the memory device returned to its normal operating state by performing a  $\overline{\text{RAS}}$ -only refresh cycle or a  $\overline{\text{CAS}}$  before  $\overline{\text{RAS}}$  refresh cycle.
  12. In a test mode read cycle, the value of access time parameters is delayed for 5 ns for the specified value. These parameters should be specified in test mode cycle by adding the above value to the specified value in this data sheet.
  13. These parameters are determined by the falling edge of either  $\overline{\text{CAS1}}$  or  $\overline{\text{CAS2}}$ , whichever is earlier.
  14. These parameters are determined by the rising edge of either  $\overline{\text{CAS1}}$  or  $\overline{\text{CAS2}}$ , whichever is later.
  15.  $t_{CWL}$  should be satisfied by both  $\overline{\text{CAS1}}$  and  $\overline{\text{CAS2}}$ .
  16.  $t_{CP}$  is determined by the time both  $\overline{\text{CAS1}}$  and  $\overline{\text{CAS2}}$  are high.



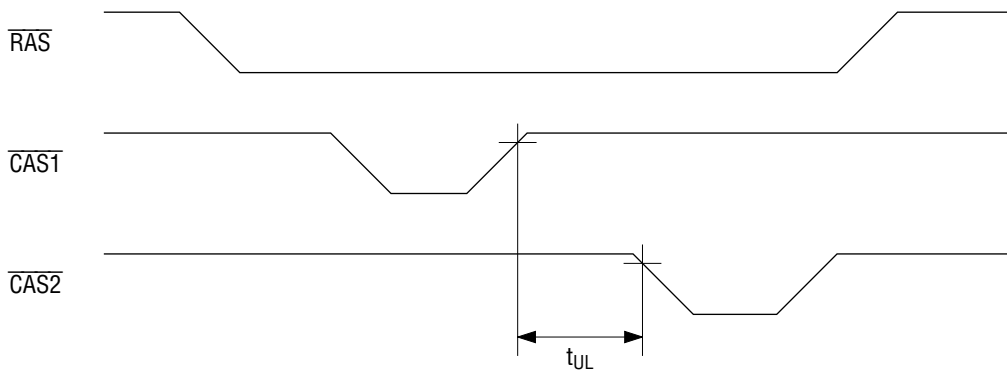
**Notes concerning  $\overline{\text{CAS1}}$  and  $\overline{\text{CAS2}}$  control**

Overlap the active-low timings of  $\overline{\text{CAS1}}$  and  $\overline{\text{CAS2}}$ . Skew between  $\overline{\text{CAS1}}$  and  $\overline{\text{CAS2}}$  is allowed under the following conditions:

- (1) The timing specification for  $\overline{\text{CAS1}}$  and  $\overline{\text{CAS2}}$  should be met individually.
- (2) Different operation modes for  $\overline{\text{CAS1}}/\overline{\text{CAS2}}$  are not allowed (as shown below).

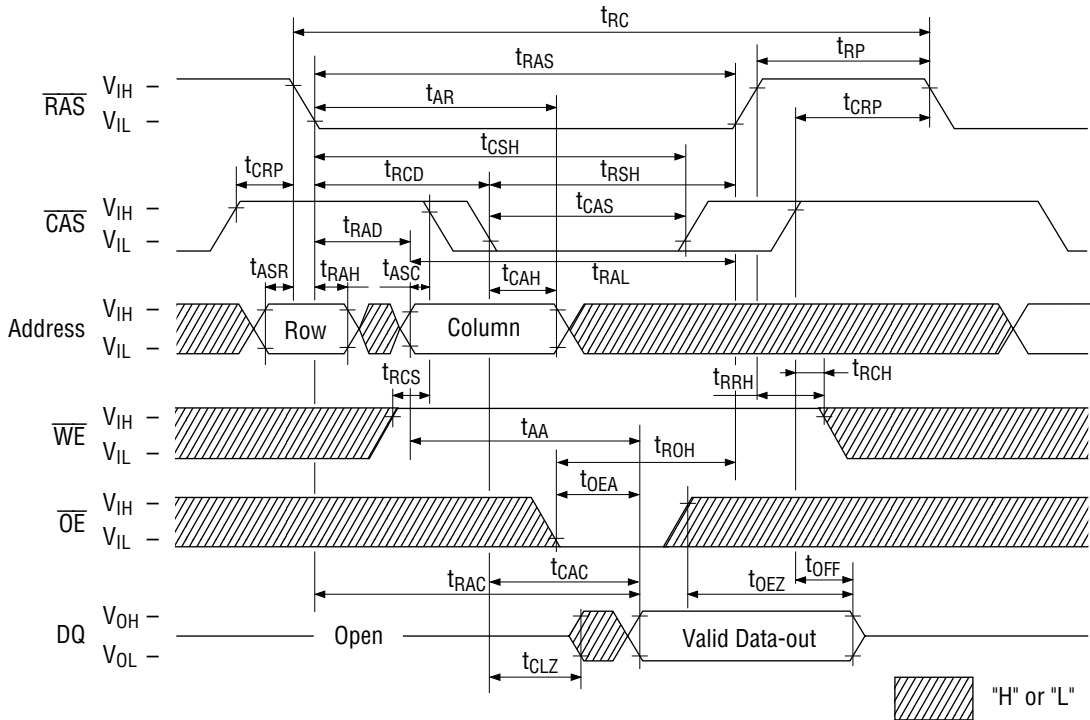


- (3) Closely separated  $\overline{\text{CAS1}}/\overline{\text{CAS2}}$  control is not allowed. However, when the condition ( $t_{\text{CP}} \leq t_{\text{UL}}$ ) is satisfied, fast page mode can be performed.

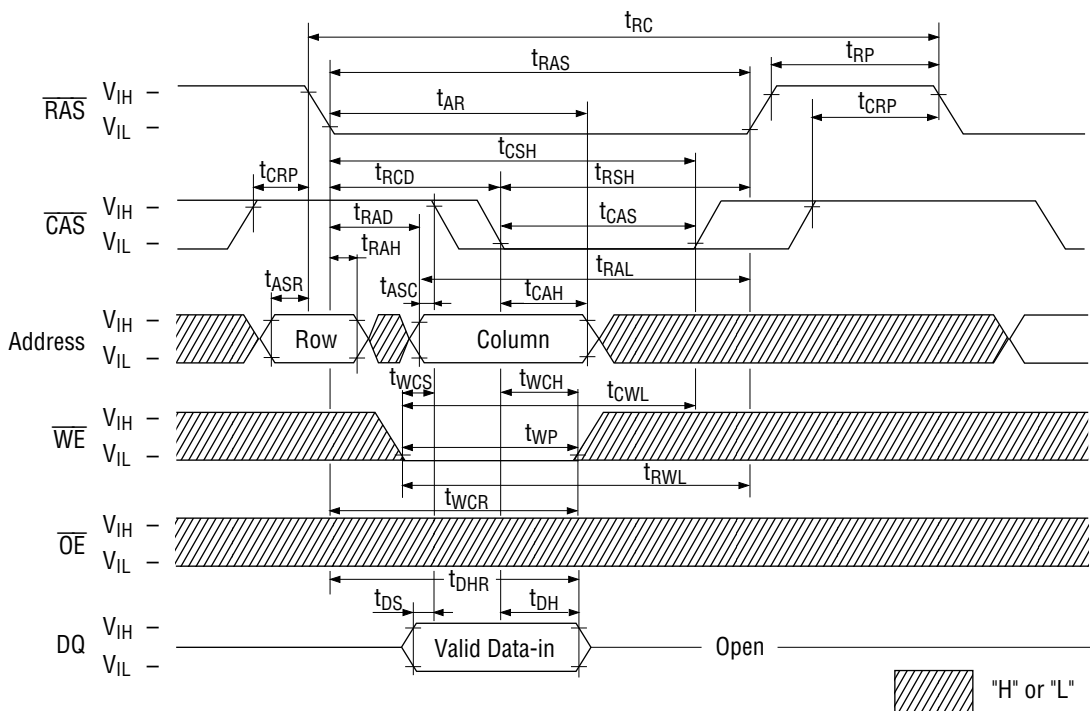


TIMING WAVEFORM

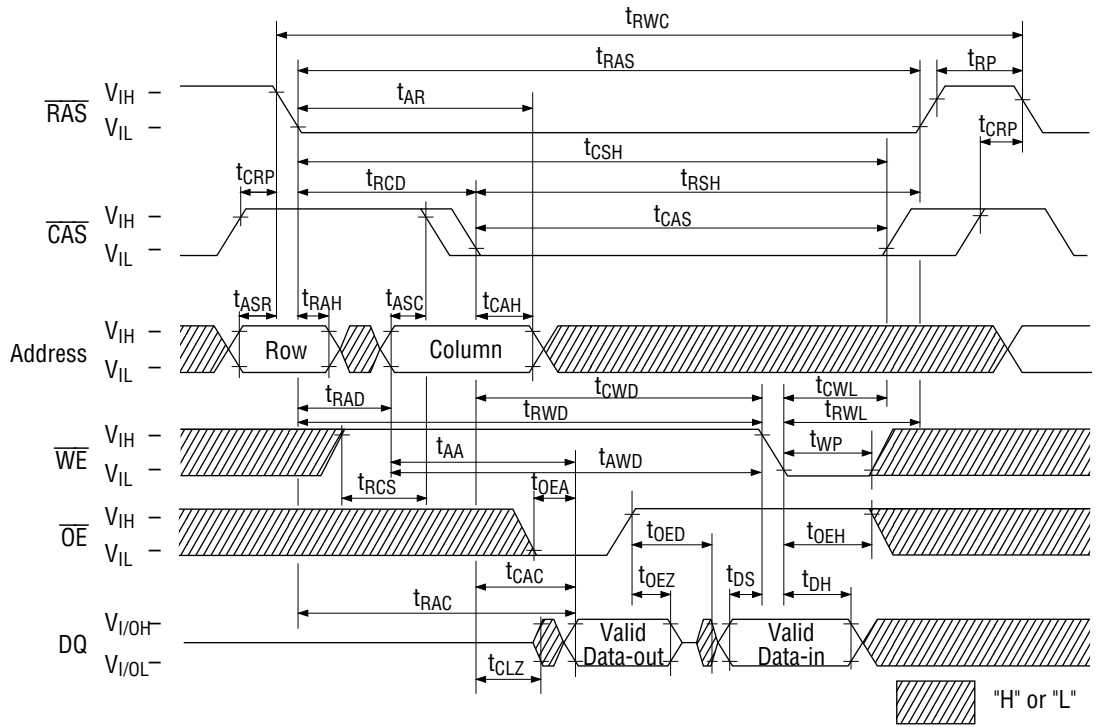
Read Cycle



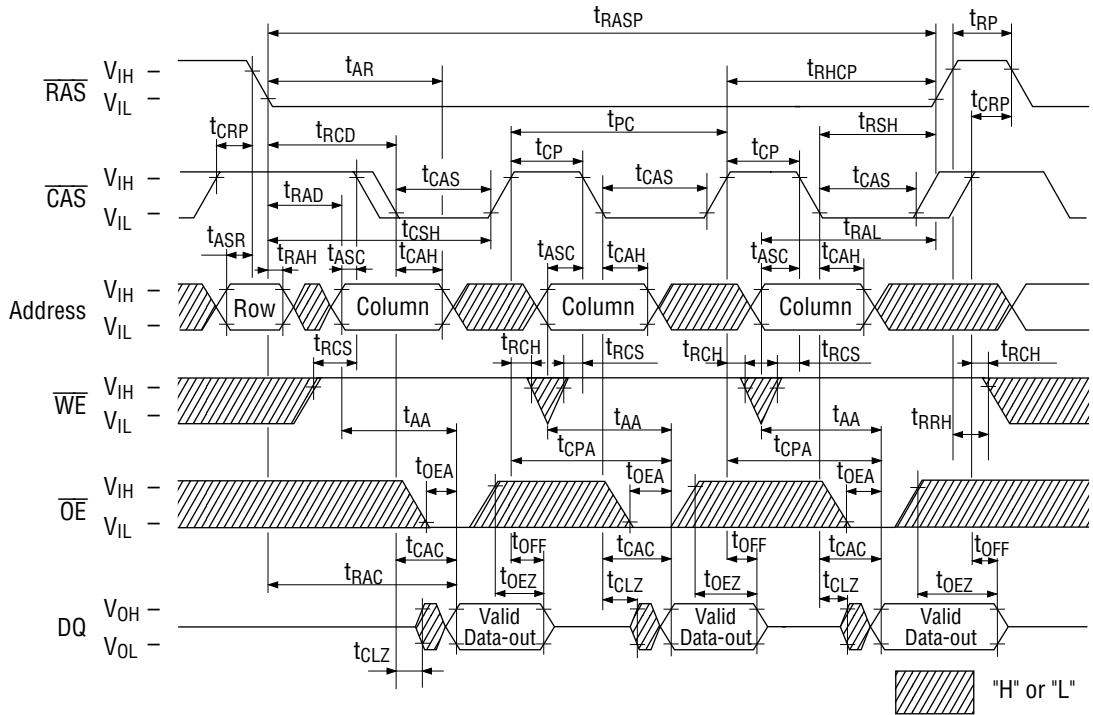
Write Cycle (Early Write)



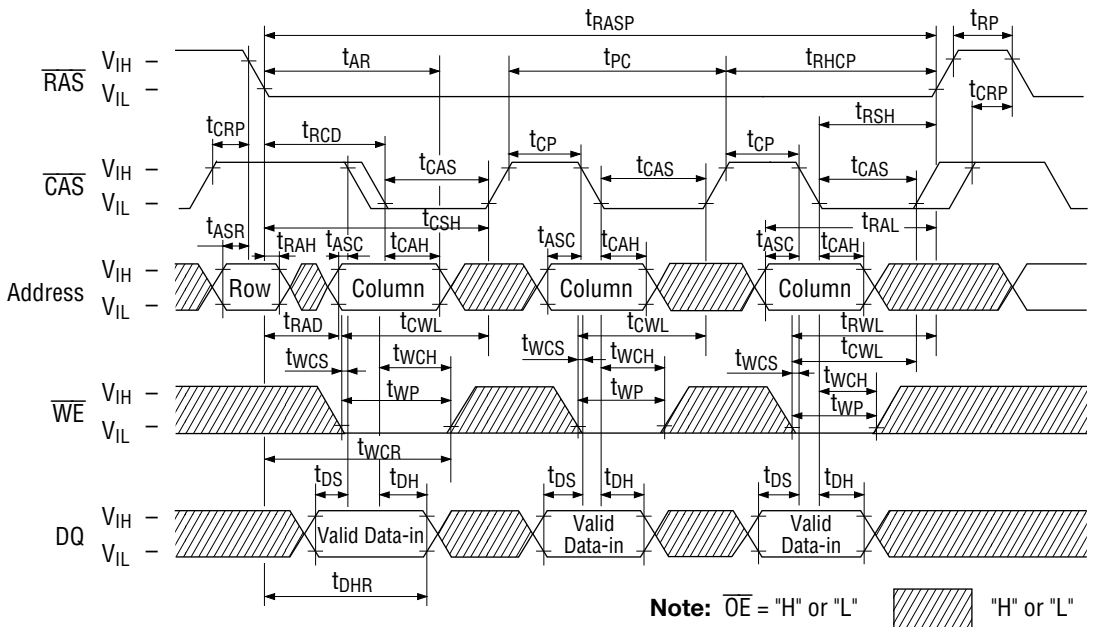
Read Modify Write Cycle



Fast Page Mode Read Cycle

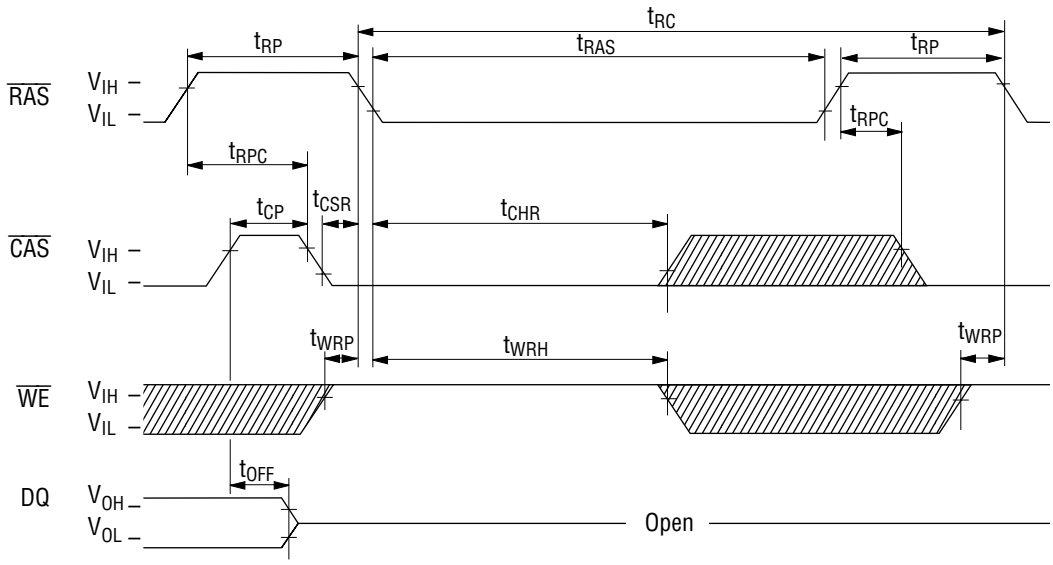



Fast Page Mode Write Cycle (Early Write)



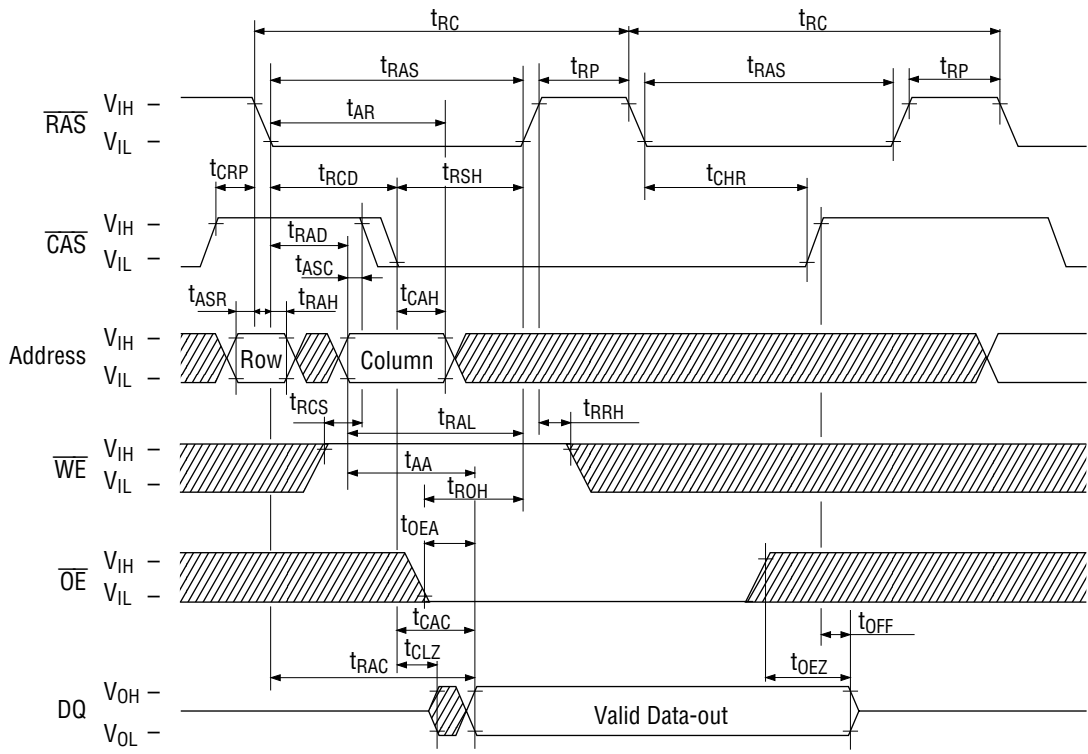


**CAS before RAS Refresh Cycle**



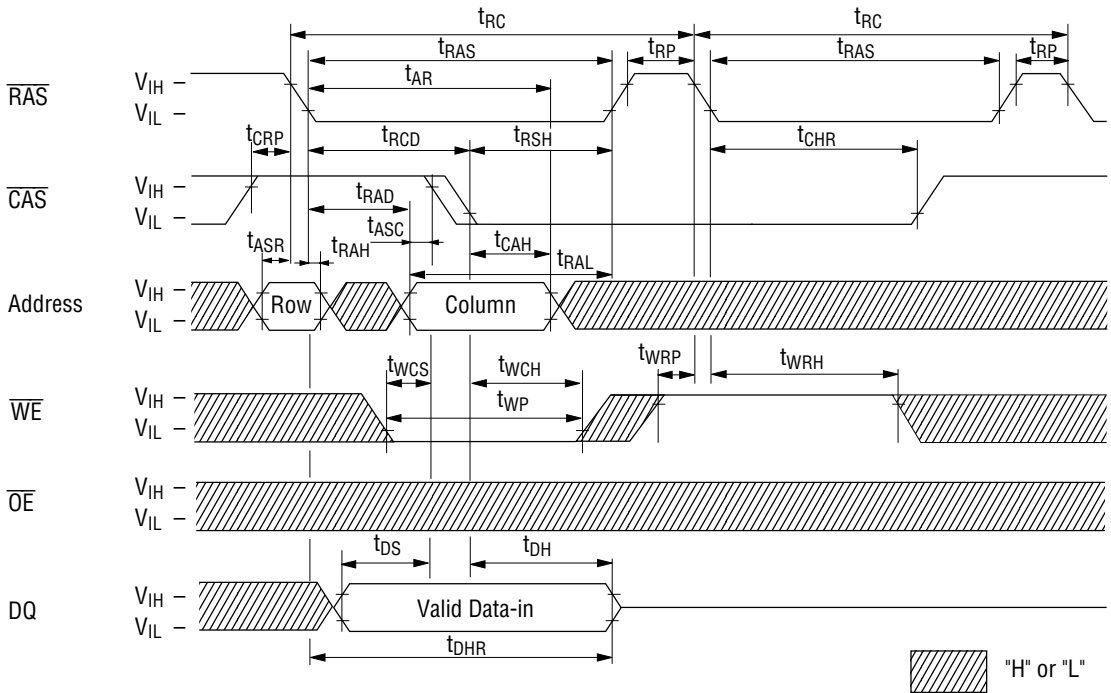
**Note:**  $\overline{OE}$ , Address = "H" or "L"  "H" or "L"

**Hidden Refresh Read Cycle**

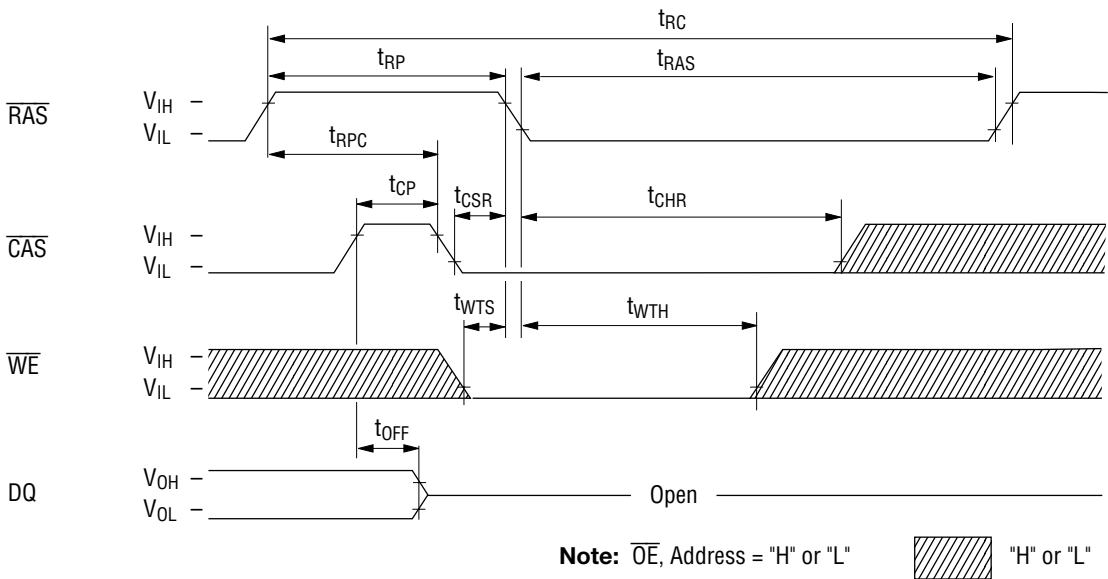


 "H" or "L"

**Hidden Refresh Write Cycle**



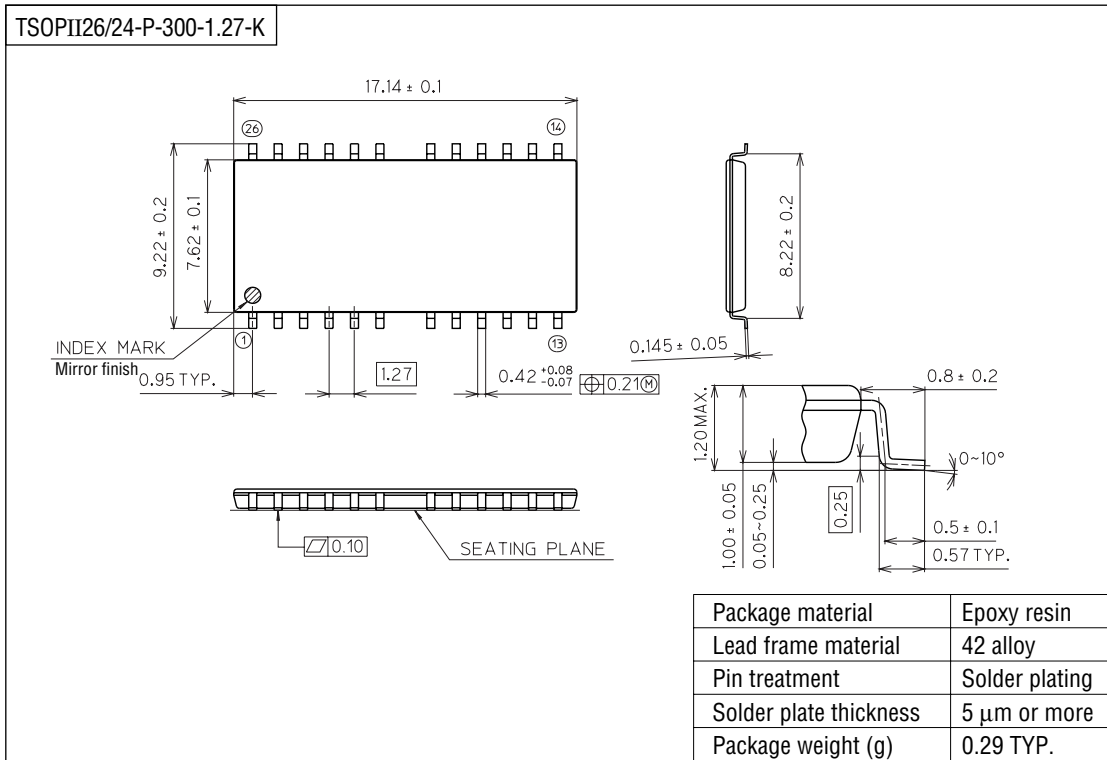
**Test Mode Initiate Cycle**







(Unit : mm)



Notes for Mounting the Surface Mount Type Package

The SOP, QFP, TSOP, SOJ, QFJ (PLCC), SHP and BGA are surface mount type packages, which are very susceptible to heat in reflow mounting and humidity absorbed in storage. Therefore, before you perform reflow mounting, contact Oki's responsible sales person for the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).