# EM-1712

Shipped in packet-tape reel(5000pcs/Reel)

EM-1712 is ultra-small Hall effect ICs of a single silicon chip composed of Hall element and a signal processing IC.

Bipolar Hall Effect Latch Supply Voltage 1.6~5.5V

Power down Function

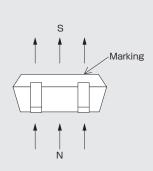
Ultra High Sensitivity Bop: 1.8mT

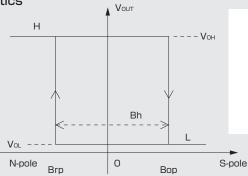
Output **CMOS** 

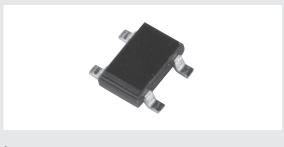
**SMT** 

Notice: It is requested to read and accept "IMPORTANT NOTICE" written on the back of the front cover of this catalogue.

# Operational Characteristics







Magnetic flux density

# ●Absolute Maximum Ratings (Ta=25°C)

Item	Symbol	Min.	Max.	Unit
Supply Voltage	V <sub>DD</sub>	-0.1	6.0	V
PDN input voltage	VIN	-0.1	V <sub>DD</sub> +0.1	V
PDN input current	lin	-10	+10	mA
Output Current	Іоит	-0.5	+0.5	mA
Storage Temperature Range	Тѕтс	-40	+125	°C

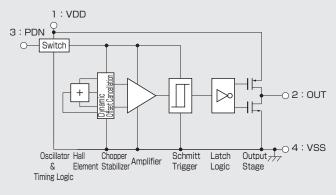
# Recommended Operating Conditions

Item	Symbol	Min.	Тур.	Max.	Unit
Supply Voltage	V <sub>DD</sub>	1.6	3.0	5.5	V
Operating Temperature Range	Topr	-30	+25	+85	$^{\circ}$

## ■Magnetic ① and Electrical Characteristics (Ta=25°C VDD=3.0V)

Item	Symbol	Conditions	Min.	Тур.	Max.	Unit
Operating Point *1	Вор			1.8	4.0	mT
Releasing Point *1	Brp		-4.0	-1.8		mT
Hysteresis	Bh			3.6		mT
PDN input High voltage	VIH		0.7V <sub>DD</sub>			V
PDN input Low voltage	VIL				0.3	V
Output High Voltage	Vон	lo=-0.5mA	V <sub>DD</sub> -0.4			V
Output Low Voltage	Vol	Io=+0.5mA			0.4	V
Supply Current1*2	loo1	PDN=L			1	μΑ
Supply Current2*2	loo2	PDN=H,Average		60	150	μΑ
PDN input Current	IIN		-1		1	μΑ
PDN mode transition time1*3	T <sub>PD</sub> 1	Active→PDN			(36.6)	μs
PDN mode transition time2	T <sub>PD</sub> 2	PDN→Active			100	μs

# Functional Block Diagram



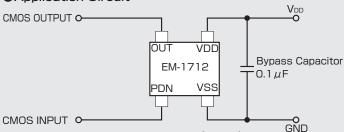
Item	Symbol	Conditions	Min.	Тур.	Max.	Unit
Pulse Drive Period	T <sub>PD</sub> 3	PDN=H	0.5	1.0	1.5	ms
PDN input Pluse Width	Tw		100			μs
Pulse Drive Time	T <sub>PD</sub> 4	PDN=H	12.2	24.4	36.6	μs

# ■Magnetic Characteristics ② (Ta=-30~+85°C VDD=3.0V)

Parameter	Symbol	Conditions	Min.	Тур.	Max.	Unit
Operating Point	Вор			1.8	4.2	mT
Releasing Point	Brp		-4.2	-1.8		mT
Hysteresis	Bh			3.6		mT

Note) The above specifications are design targets.

### Application Circuit



- \*1: Positive("+") polarity flux is defined as the magnetic flux from south polewhich is direct toward to the branded face of the sensor (Bop,Brp) \*2: In case of PDN pin is held at VDD or GND.
  \*3: This transition time is not guarantee

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#### Package (Unit:mm) ●(For reference only)Land Pattern (Unit:mm) 0.25 0.50 03 2 i φ0.3 2.1±0.2 0~0.1 Sensor center 0.90 25 90 3 0.05 0.1 Sensor Note 1) The sensor center is located within the $\phi$ 0.3mm circle. 0.55 ന Note2) The tolerances of dimensions with no mentions is $\pm 0.1$ mm. Note3) Coplanarity: The differences between <u>5°</u> standoff of terminals are max.0.1mm. 1.30 Pin No. Note4) The sensor part is located 0.4mm(typ.) Pin Name | Function far from marking surface. VDD Power Supply OUT Output PDN Power Down

# Function Timing Chart 1 B [mT] N O Undefined T<sub>PD</sub>1(<36.6μs) T<sub>PD</sub>1(<36.6μs) T<sub>PD</sub>1(<36.6μs)

# Note1) During power down mode, output is latched in its previous state.

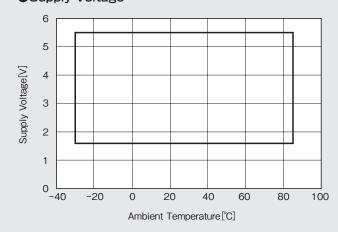
Note2) When VDD is supplied, the time from reaching  $V_{DD}$ = 1.6V to the update of the output state is equal to  $T_{PD}2$ .

**Functional Timing** 

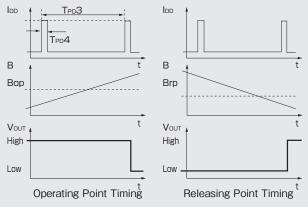
# Supply Voltage

VSS

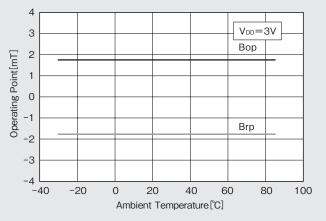
Ground



# ●Function Timing Chart 2 (PDN=H)



# ●Temperature Dependence of Bop. Brp



j

n

0

р

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